ON SOME SPECIAL TYPES OF ε -APPROXIMATIONS FOR SET-VALUED MAPPINGS

Yuri E. Gliklikh

Voronezh State University

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Аннотация. Для полунепрерывных сверху конечномерных многозначных отображений с выпуклыми или асферичными замкнутыми значениями мы доказываем существование специальных непрервных $\boldsymbol{\varepsilon}$ -аппроксимаций, которые поточечно сходятся к измеримому по Борелю селектору многозначного отображения при $\boldsymbol{\varepsilon}$, стремящимся к нулю. Для выпуклозначного случая сходимость имеет место на всей области определения, а для отображений с асферичными значениями — на некотором счетном всюду плотном подмножестве.

Ключевые слова: Полунепрерывные сверху многозначные отображения; выпусклые замкнутые значения; асферичные замкнутые значения; *є* -аппроксимации; поточечная сходимость.

Abstract. For upper semicontinuous finite-dimensional set-valued mappings with either convex closed or aspheric closed values we prove the existence of special continuous $\boldsymbol{\varepsilon}$ -approximations that point-wise converge to a Borel measurable selector of the set-valued mapping as $\boldsymbol{\varepsilon}$ tends to zero. For convex-valued case the convergence holds on the entire domain while for aspheric-valued case — on a certain countable everywhere dense subset.

Key words: Upper semicontinuous set-valued mapping; convex closed values; aspheric closed values; ε -approximations; point-wise convergence.

1. INTRODUCTION

The main aim of this paper is to show the existence of ε -approximations of the upper semicontinuous set-valued finite-dimensional map that point-wise converge to a Borel measurable selector as $\varepsilon \to 0$. Unlike the case of ordinary differential inclusions, such approximations are very much useful for investigation of stochastic differential inclusions.

Recall that $\boldsymbol{\varepsilon}$ -approximations are proved to exist for upper semicontinuious set-valued map either with convex closed values or with aspheric closed ones (see below). We consider both cases, but for convex-valued mappings we prove the existence of point-wise converging $\boldsymbol{\varepsilon}$ -approximations on the entire domain while for aspheric-valued ones only on a certain countable everywhere dense subset.

The paper is partially a survey of some results from [1,2] (convex-valued case) and partially it contains new results (aspheric-valued case).

The structure of paper is as follows. In Section 2 we give a short introduction into the Theory of Set-Valued Mappings. More details can be found, e.g., [3,4] where in particular the proofs of many results, presented here, are given.

In Section 3 we deal with convex-valued mappings. Taking into account applications to stochastic differential inclusions, we consider two classes of set-valued mappings: those depending on points of phase space and those depending on curves but non-anticipating with respect to a special filtration generated by σ -algebras of cylinder sets. We prove the existence of point-wise converging sequences of ε -approximation depending on points or non-anticipating with respect to the same filtration, respectively.

In Section 4 we construct a sequence of ε -approximations for aspheric-valued mappings that point-wise converge to a selector on a countable everywhere dense subset Ξ . In this case for every point of Ξ there exists a number such that for all greater numbers the values of all terms of the sequence at that point are stabilized (i.e., have the same value).

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2. A BRIEF INTRODUCTION INTO THE THEORY OF SET-VALUED MAPPINGS

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A set-valued mapping F from a set X into a set Y is a correspondence that assigns a nonempty subset $F(x) \subset Y$ to every point $x \in X$; F(x) is called the value of x.

In order to distinguish set-valued mappings form single-valued ones we shall denote a setvalued mapping F sending X to Y, by the symbol $F: X \rightarrow Y$ while for a single-valued mapping we shall keep the notation $f: X \rightarrow Y$.

If X and Y are metric spaces, for set-valued mappings there are several different analogues of continuity that in the case of single-valued mappings are transformed into the usual one (here we do not deal with the description of such notion for set-valued mappings of topological spaces, see, e.g., [3]).

Definition 1. A set-valued mapping F is called upper semicontinuous at the point $x \in X$ if for each $\varepsilon > 0$ there exists a neighbourhood U(x) of x such that from $x' \in U(x)$ it follows that F(x') belongs to the ε -neighbourhood of the set F(x). F is called upper semicontinuous on X if it is upper semicontinuous at every point of X.

Definition 2. A set-valued mapping F is called lower semicontinuous at the point $x \in X$ if for each $\varepsilon > 0$ there exists a neighbourhood U(x) of x such that from $x' \in U(x)$ it follows that F(x) belongs to the ε -neighbourhood of F(x'). F is called lower semicontinuous on X if it is lower semicontinuous at every point of X.

Definition 3. If F is both upper and lower semicontinuous, it is called continuous (sometimes is also called Hausdorff continuous).

The continuous set-valued mapping F such that for each x its value F(x) is a closed bounded set, are continuous with respect to the so called Hausdorff metric on the space of all non-empty closed bounded subsets in Y. In order to describe it we first introduce the submetric $\overline{H}(A, B) = \sup_{a \in A} \rho(a, B)$ where

ho is the metric in Y . Then the Hausdorff metric is defined by the formula

$$H(A,B) = \max(\overline{H}(A,B),\overline{H}(B,A)).$$
(1)

A set-valued mapping is called closed if its graph is a closed subset in $X \times Y$. If F is closed and for each point $x \in X$ there exists a neighbourhood U(x) such that F(U(x)) is relatively compact, F is upper semicontinuous.

Definition 4. We say that F(t, x) satisfies upper Carathéodory conditions if:

1) for every $x \in X$ the map $F(\cdot, x) : I \multimap Y$ is measurable,

2) for almost all $t \in I$ the map $F(t, \cdot) : X \multimap Y$ is upper semicontinuous.

Definition 5. Let $I = [0, l] \subset R$. The set-valued mapping $F: I \times X \multimap Y$ is called almost lower semicontinuous if there exists a countable sequence of disjoint compact sets $\{I_n\}$, $I_n \subset I$ such that: (i) the measure of $I \setminus \bigcup_n I_n$ is equal to zero; (ii) the restriction of F on each $I_n \times X$ is lower semicontinuous.

An important technical role in investigating set-valued mappings is played by single-valued mappings that approximate the set-valued ones in some sense. We describe two kinds of such single-valued mappings: selectors and ε -approximations.

Definition 6. Let $F: X \to Y$ be a set-valued mapping. A single-valued mapping $f: X \to Y$ such that for each $x \in X$ the inclusion $f(x) \in F(x)$ holds, is called a selector of F.

Not every set-valued mapping has a continuous selector. For lower semicontinuous set-valued mappings with convex closed values their existence is proved in the classical Michael's Theorem.

Theorem 7. (Michael's Theorem) If X is an arbitrary metric space and Y is a Banach space, a lower semicontinuous mapping such that the value of every point of X is a convex closed set, has a continuous selector.

If the values of a lower semicontinuous set-valued mapping (generally speaking) are not convex, it may not have continuous selectors. Then the following construction is often very much useful.

Definition 8. Let E be a separable Banach space. A non-empty set $\mathcal{M} \subset L^1([0,l]; E)$ is called decomposable if $f * \chi_m + g * \chi_{[0,l] \setminus m} \in \mathcal{M}$ for all $f, g \in \mathcal{M}$ and for every measurable subset m in [0,l] where χ is the characteristic function of the corresponding set.

The reader can find more details about decomposable sets in [4] and [5].

Theorem 9. (Bressan–Colombo Theorem) Consider a separable metric space (Ω, d) . Let X be a Banach space and (J, \mathcal{A}, μ) be a measurable space with a σ -algebra \mathcal{A} and a non-atomic measure μ such that $\mu(J) = 1$. Consider the space $Y = L_X^1(J, \mathcal{A}, \mu)$ of integrable mappings from (J, \mathcal{A}, μ) into X. If a set-valued mapping $F : \Omega \multimap Y$ is lower semicontinuous and has close decomposable values, F has a continuous selector.

The assertion of Theorem 9 is proved, e.g., as Lemma 9.2 in [5].

Upper semicontinuous mappings arise in applications more often than lower semicontinuous ones. Generally speaking, they do not have continuous selectors (but they have measurable ones). The so called ε -approximations are very much useful for investigating the upper semicontinuous mappings.

Definition 10. For given $\varepsilon > 0$ a continuous single-valued mapping $f_{\varepsilon} : X \to Y$ is called an ε -approximation of a set-valued mapping $F : X \multimap Y$ if the graph of f as a set in $X \times Y$, belongs to the ε -neighbourhood of the graph of F.

We mention the following classes of upper semicontinuous set-valued mappings of finitedimensional spaces, for which the existence of ε -approximations is proved for each $\varepsilon > 0$:

- the mappings with convex closed values;

— the so called mappings with values that are aspheric in all dimensions from 1 to n-1and weakly aspheric in the dimension n (see [6]). This class of of set-valued mappings was first time considered by A. D. Myshkis in 1954 [7]. In [6] and [8] topological characteristics of topological index and Lefschetz number types were constructed for such mappings. Later (in 80-th years of XX century) this class was rediscovered and called "the mappings whose values at every point have the so-called uv^k -property for k = 1, ..., n" (see exact definition, e.g., in [9]).

Let X be a Banach space and $F: X \multimap X$ be an upper semicontinuous set-valued mapping with convex closed values. Let also for each bounded subset $\Omega \subset X$ its image $F(\Omega)$ is relatively compact. Then if F sends a ball B of X into itself, in B there exists a fixed point $x \in F(x)$ of F (an analog of Schauder's principle known as Glicksberg-Ky Fan Theorem).

Let $F : R \times R^n \longrightarrow R^n$ be a set-valued mapping. A differential inclusion

$$\dot{x} \in F(t, x) \tag{2}$$

is an analogue of differential equation and transforms into the latter if F is single-valued.

A solution of (2) is an absolutely continuous curve x(t) such that (2) is satisfied for it almost everywhere.

If F is upper semicontinuous and has convex closed bounded values, for each couple $x_0 \in \mathbb{R}^n$, $t_0 \in \mathbb{R}$ there exists a local in time solution of (2) with the initial condition $x(t_0) = x_0$. It is also known that for an upper semicontinuous F with closed bounded (not necessarily convex) values there exists a solution of Cauchy problem for the differential inclusion $\dot{x} \in coF(t, x),$

where coF(t, x) is the convex closure of F(t, x).

Existence of solutions of (2) for lower semicontinuous F is possible also for non-covex values. Often such existence can be proved by applying Bressan-Colombo Theorem 9.

3. SPECIAL ε - APPROXIMATIONS FOR CONVEX-VALUED UPPER SEMI-CONTINUOUS MAPPINS

Here, following [1, 2], we prove existence of special ε -approximations for upper semicontinuous mappings in finite-dimensional spaces with convex closed values such that they point-wise converge to a Borel measurable selector of the set-valued mapping as $\varepsilon \to 0$.

Theorem 11. Let $\Phi : \mathbb{R}^n \to \mathbb{R}^n$ be an upper semi-continuous set-valued map with convex closed bounded values. For a sequence $\varepsilon_i \to 0$ there exists a sequence of continuous ε_i approximations for Φ that point-wise converges to a Borel measurable selector of Φ . If Φ takes values in a convex set Ξ in \mathbb{R}^n , those ε -approximations take values in Ξ as well.

Proof. It is shown in [10] that in the case under consideration for any $\boldsymbol{\varepsilon}_i$ there exists a lower semi-continuous set-valued map $\Psi_i: \mathbb{R}^n \to \mathbb{R}^n$ with closed convex bounded values such that: (i) for any $x \in \mathbb{R}^n$ the inclusion $\Phi(x) \subset \Psi_i(x)$ holds and (ii) the graph of Ψ_i belongs to the ε_i -neighbourhood of the graph of Φ . From the construction it follows that if Φ takes values in a convex set Ξ in \mathbb{R}^n , then the values of all $\Psi_i(x)$ belong to Ξ . Notice that for an upper semi-continuous mapping with compact values the sum of such mappings and the products with a continuous function are upper semi-continuous. Hence, from the proof of Theorem 2 [10] it follows that in the case under consideration all Ψ_i are continuous set-valued mapping and, in particular in our case, they are continuous with respect to Hausdorff metric.

Consider the minimal selector $\boldsymbol{\psi}_i(\cdot)$ of $\boldsymbol{\Psi}_i(\cdot)$, i.e., $\boldsymbol{\psi}_i(x)$ is the closest to origin point in $\boldsymbol{\Psi}_i(x)$, $x \in \mathbb{R}^n$. We refer the reader to [11] for complete description of minimal selectors. In particular, it is shown there that minimal selectors are continuous. Thus, $\boldsymbol{\psi}_i$ is an $\boldsymbol{\varepsilon}_i$ -approximation of $\boldsymbol{\Phi}$.

Specify an arbitrary point $x \in \mathbb{R}^n$. Since $\Phi(x) \subset \Psi_i(x)$ for each *i*, for the Hausdorff submetric \overline{H} we have $\overline{H}(\Phi(x), \Psi_k(x)) = 0$. Hence

for the Hausdorff metric H we obtain that $H(\Psi_i(x), \Phi(x)) = \overline{H}(\Psi_i(x), \Phi(x))$ for each i.

Now specify ε_k . By definition of upper semicontinuity for any $x \in \mathbb{R}^n$ there exists $\delta_k > 0$ such that for any x' from δ_k -neighbourhood of x the value $\Phi(x')$ belongs to the ε_k -neighbourhood of $\Phi(x)$. Since $\varepsilon_i \to 0$, $\varepsilon_{k+l} < \delta_k$ for some l = l(k, x)and without loss of generality we may take $l(k, x) \ge 0$. Thus $\overline{H}(\Phi(x'), \Phi(x)) < \varepsilon_k$ for each x'from ε_{k+l} -neighbourhood of x.

Since the graph of Ψ_{k+l} belongs to ε_{k+l} -neighbourhood of the graph of Φ , there exists a point x'' in the ε_{k+l} -neighbourhood of x such that $\Psi_{k+l}(\underline{x})$ belongs to ε_{k+l} -neighbourhood of $\Phi(x'')$, i.e., $\overline{H}(\Psi_{k+l}(x), \Phi(x'')) < \varepsilon_{k+l}$.

Thus

$$\begin{split} H(\Psi_{k+l}(x), \Phi(x)) &= H(\Psi_{k+l}(x), \Phi(x)) \leq \\ &\leq \overline{H}(\Psi_{k+l}(x), \Phi(x'')) + \overline{H}(\Phi(x''), \Phi(x)) < \\ &< \varepsilon_{k+l} + \varepsilon_k < 2\varepsilon_k. \end{split}$$

Hence at each x the convex set $\Psi_i(x)$ tends to the convex set $\Phi(x)$ with respect to Hausdorff metric as $i \to \infty$. Then $\psi_i(x)$ tends to the point $\varphi(x) \in \Phi(x)$ that is the closest to the origin. The fact that the point-wise limit $\varphi(\cdot)$ of the sequence of continuous mappings $\psi_i(\cdot)$ is a Borel measurable mapping, completes the proof.

Introduce $\hat{\Omega} = C^0([0,T], \mathbb{R}^n)$, the Banach space of continuous curves in \mathbb{R}^n given on [0,T], with usual uniform norm, and the σ -algebra $\tilde{\mathcal{F}}$ on $\tilde{\Omega}$ generated by cylinder sets. By \mathcal{P}_t we denote the σ -subalgebra of \mathcal{F} generated by cylinder sets with bases over $[0,t] \subset [0,T]$. Recall that $\tilde{\mathcal{F}}$ is the Borel σ -algebra on $\tilde{\Omega}$ (see [12]).

Let $B:[0,T] \times \Omega \to Z$ be a mapping to some metric space Z. Below we shall often suppose that such mappings with various spaces Z satisfy the following condition:

Condition 12. For each $t \in [0,T]$ from the fact that the curves $x_1(\cdot)$, $x_2(\cdot) \in \tilde{\Omega}$ coincide for $0 \le s \le t$, it follows that $B(t, x_1(\cdot)) = B(t, x_2(\cdot))$.

Remark 13. Note that the fact that a mapping *B* satisfies Condition 12, is equivalent to the fact that *B* at each *t* is measurable with respect to Borel σ -algebra in *Z* and \mathcal{P}_t in $\tilde{\Omega}$, see [13].

Theorem 14. Specify an arbitrary sequence of positive numbers $\varepsilon_k \to 0$ as $k \to \infty$. Let **B** be an upper semi-continuous set-valued mapping with compact convex values sending $[0,T] \times \tilde{\Omega}$ to a finite-dimensional Euclidean vector space Y and satisfying Condition 12. Then there exists a sequence of continuous single-valued mappings $B_k:[0,T] \times \tilde{\Omega} \to Y$ with the following properties:

(i) each B_k satisfies Condition 12;

(ii) the sequence B_k point-wise converges to a selector of \boldsymbol{B} that is measurable with respect to Borel $\boldsymbol{\sigma}$ -algebra in Y and the product $\boldsymbol{\sigma}$ -algebra of Borel one on [0,T] and $\tilde{\mathcal{F}}$ on $\tilde{\Omega}_{2}^{\circ}$;

(iii) at each $(t, x(\cdot)) \in [0, T] \times \hat{\Omega}$ the inequality $||B_k(t, x(\cdot))|| \le ||B(t, x(\cdot))||$ holds for all k;

(iv) if **B** takes values in a closed convex set $\Xi \subset Y$, the values of all B_{\downarrow} belong to Ξ .

Proof. In this proof we combine and modify the ideas used in the proofs of [10] by Gel'man and Theorem 11 above.

For $t \in [0, T]$ introduce the mapping $f_t : \Omega \to \Omega$ by the formula

$$f_t x(\cdot) = \begin{cases} x(s) \text{ if } 0 \le s \le t\\ x(t) \text{ if } t \le s \le T. \end{cases}$$
(3)

Obviously $f_t x(\cdot)$ is continuous jointly in $t \in [0, T]$ and $x(\cdot) \in \tilde{\Omega}$. Since **B** satisfies Condition 12, $B(t, x(\cdot)) = B(t, f_t x(\cdot))$ for each $x(\cdot) \in \tilde{\Omega}$ and $t \in [0, T]$.

Specify an element $\boldsymbol{\varepsilon}_k$ from the sequence. Since B is upper semi-continuous, for every $(t, x(\cdot)) \in [0, T] \times \Omega$ there exists $\delta_k(t, x) > 0$ such that for every $(t^*, x^*(\cdot))$ from the $\delta_k(t, x)$ neighbourhood of $(t, x(\cdot))$ the set $B(t^*, x^*(\cdot))$ is contained in the $\frac{\mathcal{E}_k}{2}$ -neighbourhood of the set $B(t, x(\cdot))$. Without loss of generality we can suppose $0 < \delta_k(t, x) < \varepsilon_k$ for every $(t, x(\cdot))$. Consider the $\frac{\boldsymbol{\delta}_{\boldsymbol{k}}(t,\boldsymbol{x})}{\boldsymbol{\Delta}} \text{-neighbourhood of } (t,\boldsymbol{x}(\cdot)) \text{ in } [0,T] \times \tilde{\boldsymbol{\Omega}}$ and construct the open covering of $[0,T] \times \tilde{\Omega}$ by such neighbourhoods for all $(t, x(\cdot))$. Since $[0,T] \times \Omega$ is paracompact, there exists a locally finite refinement $\{V_j^k\}$ of this covering. Without loss of generality we can consider each V_i^k as an $\eta_k(t_j^k, x_j^k)$ -neighbourhood of a certain $(t_j^k, x_j^k(\cdot))$ where by construction the radius $\eta_k(t_j, x_j) \leq \frac{\delta_k(t_j, x_j)}{4}$.

Consider a continuous partition of unity
$$\{\boldsymbol{\varphi}_{j}^{k}\}$$

adapted to $\{V_{j}^{k}\}$ and introduce the set-valued
mapping $\boldsymbol{\Phi}_{k}(t, x(\cdot)) = \sum_{j} \boldsymbol{\varphi}_{j}^{k}(t, x(\cdot)) \overline{co} \boldsymbol{B}(V_{j}^{k})$ where
 \overline{co} denotes the convex closure. Since $\boldsymbol{B}(t, x(\cdot))$ is
upper semi-continuous and has compact values,
without loss of generality we can suppose $\boldsymbol{\delta}_{k}(t, x)$
to be such that the images $\boldsymbol{B}(V_{j}^{k})$ are bounded in
 Y and so the sets $\overline{co}\boldsymbol{B}(V_{i}^{k})$ are compact. Denote

by $\overline{\Phi}_k(t, x(\cdot))$ the closure of $\Phi_k(t, x(\cdot))$. Then one can easily see that $\overline{\Phi}_k : [0, T] \times \tilde{\Omega} \to Y$ is a Hausdorff continuous set-valued mapping with compact convex values.

Introduce $\Psi_k : [0,T] \times \tilde{\Omega} \to Y$ by formula $\Psi_k(t,x(\cdot)) = \Phi_k(t,f_tx(\cdot))$ and consider the set-valued mapping $\overline{\Psi}_k(t,x(\cdot))$. Since f_t is continuous, every $\overline{\Psi}_k$ is a Hausdorff continuous set-valued mapping with compact convex values and by construction it satisfies Condition 12.

The couple $(t, f_t x(\cdot))$ belongs to a finite collection of neighbourhoods $V_{j_i}^k$ with centers at $(t_{j_i}^k, x_{j_i}^k(\cdot))$, i = 1, ..., n and so by construction $\boldsymbol{B}(t, x(\cdot)) = \boldsymbol{B}(t, f_t x(\cdot)) \subset \boldsymbol{B}(V_{j_i}^k)$ for each i. Hence $\boldsymbol{B}(t, x(\cdot)) = \boldsymbol{B}(t, f_t x(\cdot)) \subset \Psi_k(t, x(\cdot))$ for every couple $(t, x(\cdot))$.

Let l be the number from the collection of indices j_i as above such that $\eta_k(t_l^k, x_l^k)$ takes the greatest value among $\eta_k(t_j^k, x_j^k)$. Then all $(t_{j_i}^k, x_{j_i}^k(\cdot))$ are contained in the $2\eta_k(t_l^k, x_l^k)$ -neighbourhood of $(t_l^k, x_l^k(\cdot))$ and so every $V_{j_i}^k$ is contained in $3\eta_k(t_l^k, x_l^k)$ -neighbourhood of $(t_l^k, x_l^k(\cdot))$ that is contained in $\delta_k(t_l^k, x_l^k(\cdot))$ -neighbourhood of (t_l^k, x_l^k) by construction. Then, also by construction, $\Psi_k(t, x(\cdot))$ belongs to the $\frac{\varepsilon_k}{2}$ -neighbourhood of

 $\boldsymbol{B}(t_l^k, x_l^k(\cdot))$. Since both $\boldsymbol{\Psi}_k(t, x(\cdot))$ and $\boldsymbol{B}(t_l^k, x_l^k(\cdot))$ are convex, this means that $\overline{\boldsymbol{\Psi}}_k(t, x(\cdot))$ also belongs to the $\frac{\boldsymbol{\varepsilon}_k}{2}$ -neighbourhood of $\boldsymbol{B}(t_l^k, x_l^k(\cdot))$. Notice

that this is true for each k.

Since $B(t, x(\cdot)) \subset \Psi_k(t, x(\cdot)) \subset \overline{\Psi}_k(t, x(\cdot))$, for the Hausdorff submetric \overline{H} we have

$$\overline{H}(\boldsymbol{B}(t, x(\cdot)), \overline{\boldsymbol{\Psi}}_{k}(t, x(\cdot))) = 0$$

Hence for the Hausdorff metric H we obtain that

$$H(\overline{\Psi}_k(t, x(\cdot)), \boldsymbol{B}(t, x(\cdot))) = \overline{H}(\overline{\Psi}_k(t, x(\cdot)), \boldsymbol{B}(t, x(\cdot)))$$

Since $\varepsilon_k \to 0$, for $(t, x(\cdot))$ there exists an integer $\theta = \theta(t, x(\cdot)) > 0$ such that $\varepsilon_{k+\theta} < \delta_k(t, x(\cdot))$. Without loss of generality we can suppose that $\theta \ge 1$.

Thus $\mathbf{B}(t_l^{k+ heta}, x_l^{k+ heta}(\cdot))$ belongs to the $rac{oldsymbol{arepsilon}_k}{2}$ -neigh-

bourhood of $\mathbf{B}(t, x(\cdot))$ and so

$$\bar{H}(\boldsymbol{B}(t_l^{k+\theta}, x_l^{k+\theta}(\cdot)), \boldsymbol{B}(t, x(\cdot))) < \frac{\varepsilon_k}{2}$$

Since $\overline{\Psi}_{k+\theta}(t, x(\cdot))$ belongs to the $\frac{\varepsilon_{k+\theta}}{2}$ -neighbourhood of $B(t_l^{k+\theta}, x_l^{k+\theta}(\cdot))$ (see above), we obtain that

$$\overline{H}(\overline{\Psi}_{k+\theta}(t,x(\cdot)),\boldsymbol{B}(t_l^{k+\theta},x_l^{k+\theta}))) < \frac{\boldsymbol{\varepsilon}_{k+\theta}}{2}$$

Thus

$$\begin{split} H(\overline{\mathbf{\Psi}}_{k+\theta}(t,x(\cdot)), \boldsymbol{B}(t,x(\cdot))) &= \\ &= \bar{H}(\overline{\mathbf{\Psi}}_{k+\theta}(t,x(\cdot)), \boldsymbol{B}(t,x(\cdot))) \leq \\ &\leq \bar{H}(\overline{\mathbf{\Psi}}_{k+\theta}(t,x(\cdot)), \boldsymbol{B}(t_l^{k+\theta},x_l^{k+\theta}(\cdot))) + \\ &+ \bar{H}(\boldsymbol{B}(t_l^{k+\theta},x_l^{k+\theta}(\cdot)), \boldsymbol{B}(t,x(\cdot))) < \frac{\boldsymbol{\varepsilon}_{k+\theta}}{2} + \frac{\boldsymbol{\varepsilon}_k}{2} < \boldsymbol{\varepsilon}_k. \end{split}$$

So, at each $(t, x(\cdot))$ we have that $H(\overline{\Psi}_k(t, x(\cdot)), B(t, x(\cdot))) \to 0$ as $k \to \infty$ and $B(t, x(\cdot)) \subset \Psi_k(t, x(\cdot))$ for all k.

Consider the minimal selector $B_k(t, x(\cdot))$ of $\overline{\Psi}_k(t, x(\cdot))$, i.e., $B_k(t, x(\cdot))$ is the closest to origin point in $\overline{\Psi}_i(t, x(\cdot))$. We refer the reader to [11] for complete description of minimal selectors. In particular, it is shown there that minimal selectors in our situation are continuous. By construction all B_k satisfy Condition 12.

By construction the minimal selectors $B_k(t, x(\cdot))$ of $\overline{\Psi}_k(t, x(\cdot))$ point-wise converge to the minimal selector $B(t, x(\cdot))$ of $B(t, x(\cdot))$ as $k \to \infty$ since at any $(t, x(\cdot))$ we have that $H(\overline{\Psi}_k(t, x(\cdot)), B(t, x(\cdot))) \to 0$ as $k \to \infty$ and $B(t, x(\cdot)) \subset \Psi_k(t, x(\cdot))$ for all k (see above). It is a well-known fact that the point-wise limit B of the sequence of continuous mappings B_k is measurable with respect to Borel σ -algebras in Y and in $[0, T] \times \tilde{\Omega}$ (see [14]). The latter coincides with the product σ -algebra of Borel one on [0, T] and $\tilde{\mathcal{F}}$ on $\tilde{\Omega}$ (see [12]). Properties *(iii)* and *(iv)* immediately follow from the construction.

Remark 15. Unlike $\overline{\Psi}_k(t, x(\cdot))$, the set-valued mapping $\overline{\Phi}_k(t, x(\cdot))$ may not satisfy Condition 12 since two different curves $x_1(\cdot)$ and $x_2(\cdot)$ coinciding on [0, t], may have different neighbourhoods V_j^k , to which they belong, and so the values $\overline{\Phi}_k(t, x_1(\cdot))$ and $\overline{\Phi}_k(t, x_2(\cdot))$ may be different. On the other hand, it follows from [10] that $\overline{\Phi}_k$ is an ε_k -approximation of **B** while it is not true for $\overline{\Psi}_k$.

4. SPECIAL ε-APPROXIMATIONS FOR UPPER SEMI-CONTINUOUS MAPPINGS WITH ASPHERIC CLOSED VALUES

We start this section from the exact definition of a set-valued mapping with aspheric values (see [6, 7, 8]).

Below in this section we consider a set-valued upper semi-continuous mapping $F: X \multimap E$ from a *n*-dimensional polyhedron *X* lying in some Euclidean space, to a certain Euclidean space *E*.

The assumption that X is a polyhedron does not lose generality. In particular, we can consider $F: X \multimap X$ and $F: E \multimap E$ since an Euclidean space can be presented as a polyhedron.

By O(A, r) we denote an r-neighbourhood of the set A and by d(A) — the diameter of A.

Recall that from the definition of upper semicontinuity of F it follows that for every $\varepsilon > 0$ and $\beta > 0$ there exists $\alpha(\varepsilon, \beta)$ such that in a β -neighbourhood $O(T, \beta)$ of an arbitrary set T with diameter less than α there exists a point x_0 , called *satellite* of T, for which $O(F(x_0), \varepsilon) \supset F(T)$.

Definition 16. The mapping $F: X \to X$ is called aspheric in a dimension k if in every neighbourhood $O(F(x), \varepsilon)$ of each value F(x) there exists a neighbourhood $Q(x, \varepsilon, k)$ containing $\delta = \delta(\varepsilon)$ neighbourhood of F(x) (δ does not depend on x), such that $\pi_k(Q) = 0$ where $\pi_k(Q)$ is the k-th homotopy group of Q.

Everywhere below we suppose that F is aspheric in dimensions k = 0, 1, ..., n-1. Recall that $\pi_0(Q) = 0$ means that Q is arcwise connected. For such upper semicontinuous mappings with closed values we describe the construction of ε -approximations following [6].

Let μ be a real number such that $O(F(x), \mu)$ belongs to an aspheric in dimension n-1 neighbourhood of F(x), μ does not depend on x. Construct a sequence

$$\mu > \varepsilon_{2n+1} > \varepsilon_{2n} > \delta(\varepsilon_{2n}) >$$

> $\varepsilon_{2n-1} > \ldots > \varepsilon_2 > \delta(\varepsilon_2) > \varepsilon_1,$ (4)

where $\delta(\boldsymbol{\varepsilon}_i)$ is a number that determines $\delta(\boldsymbol{\varepsilon}_i)$ neighbourhood of the value F(x) contained in $\bigcap Q(x, \boldsymbol{\varepsilon}_i, k)$. Then construct a sequence $\{\boldsymbol{\beta}_i\}_1^{n+1}$ $and a number \boldsymbol{\alpha}_0$ such that

$$0 < \boldsymbol{\beta}_{k} < \frac{1}{4} \boldsymbol{\beta}_{k+1}; \boldsymbol{\beta}_{k} + \boldsymbol{\alpha}_{0} < \boldsymbol{\alpha}(\boldsymbol{\varepsilon}_{2k+1} - \boldsymbol{\varepsilon}_{2k}, \boldsymbol{\beta}_{k+1}), (5)$$

where $\alpha(\varepsilon, \beta)$ is introduced above in this section. Such sequences evidently can be constructed starting from greater indices.

Now construct a triangulation of X whose mesh is such that the diameter of every simplex is less than $d < \min(\alpha_0, \alpha(\varepsilon_1, \beta_1))$. To every 0-dimensional simplex T_i^0 we assign a point $f(T_i^0) \in F(T_i^0)$. For every 1-dimensional simplex T_i^1 we get $d(T_i^1) < \alpha(\varepsilon_1, \beta_1)$. So, there exists a satellite x_i^1 such that $x_i^1 \in O(T_i^1, \beta_1)$ and $F(T_i^1) \subset O(F(x_i^1), \varepsilon_1)$. Hence the following inclusions take place:

$$f(T_{i_1}^0) \cup f(T_{i_2}^0) \subset F(T_i^1) \subset O(F(x_i^1), \mathcal{E}_1)$$
 (6)

and

$$O(F(x_i^1), \boldsymbol{\varepsilon}_1) \subset O(F(x_i^1), \boldsymbol{\delta}(\boldsymbol{\varepsilon}_2)) \subset \subset Q(x_i^1, \boldsymbol{\varepsilon}_2, 0) \subset O(F(x_i^1), \boldsymbol{\varepsilon}_2),$$

$$(7)$$

where $T_{i_1}^0$ and $T_{i_2}^0$ are sides of T_i^1 . Since Q is aspheric in dimension 0, f can be extended to T_i^1 as a continuous mapping and

$$f(T_i^1) \subset Q(x_i^1, \boldsymbol{\varepsilon}_2, 0) \subset O(F(x_i^1), \boldsymbol{\varepsilon}_2).$$
(8)

Let T_i^2 be a 2-dimensional simplex with 1-dimensional sides $T_{i_1}^1$, $T_{i_2}^1$ and $T_{i_3}^1$. Let $x_{i_1}^1$, $x_{i_2}^1$ and $x_{i_3}^1$ be the satellites corresponding to those sides. They form the set \tilde{T}_i^1 , for which

$$d(\tilde{T}_i^1) < 2\beta_1 + \alpha_0 < \alpha(\varepsilon_3 - \varepsilon_2, \beta_2)$$

There exists a satellite x_i^2 of , such that

$$x_i^2 \in O(\tilde{T}_i^1, \boldsymbol{\beta}_2) \text{ and } F(\tilde{T}_i^1) \subset O(F(x_i^2), \boldsymbol{\varepsilon}_2).$$

Taking into account (7) and (8) we derive

$$\bigcup_{\substack{j=1,2,3\\4}} f(T_{i_j}^1) \subset O(F(\tilde{T}_i^1), \boldsymbol{\varepsilon}_2) \subset O(F(x_i^2), \boldsymbol{\varepsilon}_2).$$
(9)
By (4) we have the inclusions

$$O(F(x_i^2), \boldsymbol{\varepsilon}_3) \subset O(F(x_i^2), \boldsymbol{\delta}(\boldsymbol{\varepsilon}_4)) \subset \\ \subset Q(x_i^2, \boldsymbol{\varepsilon}_4, 1) \subset O(F(x_i^2, \boldsymbol{\varepsilon}_4)).$$
(10)

Since $\pi_2 Q(x_i^2, \varepsilon_4, 1) = 0$, we can extend f from the boundary of simplex T_i^2 onto the entire simplex as a continuous mapping. In addition we obtain that

$$f(T_i^2) \subset Q(x_i^2, \mathcal{E}_4, 1) \subset O(F(x_i^2), \mathcal{E}_4).$$
(11)

And so on. On the last step we extend f from the (n-1)-skeleton of X onto entire X as a continuous mapping. By construction, the graph of f lies in an ε_{2n+1} -neighbourhood on the graph of F.

Theorem 17. For F as above there exists a sequence $f^{(k)}$ of continuous \mathcal{E}_{2n+1}^{k} -approximations of the type constructed above, $\mathcal{E}_{2n+1}^{k} \to 0$ as $k \to \infty$, such that for every point x of some countable everywhere dense subset $\Xi \subset X$ there exists an integer K such that for every k > K the inclusion $f^{(k)}(x) \in F(x)$ holds and $f^{(k+l)}(x) = f^{(k)}(x)$ for every integer l > 0.

Proof. By construction, for every x from the 0-dimensional skeleton of X for f constructed above, we have $f(x) \in F(x)$. Now construct a sequence of barycentric subdivisions of X. Denote by X_0^k the 0-dimensional skeleton of k-th subdivision. On every step k + 1 for $x \in X_0^k$ keep the value $f^{(k+1)}(x) = f^{(k)}(x)$ and introduce an arbitrary value $f^{(k+1)}(x) \in F(x)$ for $x \in X_0^{(k+1)} \setminus X_0^{(k)}$. Then construct continuous $f^{(k+1)}$ on the entire X in the same manner as above. The limit Ξ of $X_0^{(k)}$ as $k \to \infty$ is the set we are looking for.

Corollary 18. In notation of Theorem 17 the sequence $f^{(k)}$ on Ξ point-wise converges to a selector f of F so that for every $x \in \Xi$ the values $f^{(k)}(x)$ stabilize starting from a certain integer K(x). From the point-wise convergence if follows that f is Borel measurable on Ξ .

Remark 19. In [6,8] it is shown that under additional assumption that F is weakly aspheric in dimension n (i.e., there exists a certain $\varepsilon > 0$ such that $\pi_n Q = 0$ as in Definition 16) the homotopy class of approximations $f^{(k)}$ stabilizes for klarge enough. This allows one to introduce the homotopic characteristics for F as those for stabilized $f^{(k)}$.

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Гликлих Юрий Евгеньевич — доктор физико-математических наук, профессор кафедры алгебры и топологических методов анализа Воронежского государственного университета, тел. +7(4732)208641, e-mail: yeg@math.vsu.ru **Gliklikh Yuri E**. — ScD, Full Professor of Voronezh State University, tel. +7(4732)208641, e-mail: yeg@math.vsu.ru